

Irreducible components of the moduli stack of torsion-free sheaves of K3 surfaces and their dimensions

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1 Introduction

A moduli space is a space consisting of points that represent a certain type of object. When we consider the moduli space of sheaves, in the category of scheme, it only parametrizes the (semi) stable sheaves, which is a kind of torsion-free sheaves. If trying to realize a moduli space for all torsion-free sheaves, the concept of a stack is needed. Stack is, roughly speaking, an extension of scheme. In this study, we performed the irreducible decomposition of torsion-free sheaves on K3 surfaces and calculated the dimensions of them at each point.

2 Preliminaries

Definition 2.1 (K3 surface). X : smooth projective surface / $\mathbb{C}$

$$X : \text{K3 surface} \stackrel{\text{def}}{\iff} K_X = 0 \text{ and } H^1(X, \mathcal{O}_X) = 0$$

Definition 2.2 (Mukai vector). X : K3 surface, E : coherent sheaf on X

$$v(E) := (\text{rank}(E), c_1(E), \frac{c_1(E)^2}{2} - c_2(E) + \text{rank}(E)) \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$$

Definition 2.3 (Mukai pairing). X : K3 surface

$$v := ([v]_0, [v]_1, [v]_2), v' := ([v']_0, [v']_1, [v']_2) \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$$

$$\langle v, v' \rangle := -[v]_0[v']_2 + [v]_1[v']_1 - [v]_2[v']_0 \in \mathbb{Z}$$

Definition 2.4. $v \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$: primitive

$$\stackrel{\text{def}}{\iff} v' \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z} \text{ and } m \in \mathbb{Z}, v = mv' \Rightarrow m = 1 \text{ or } -1$$

Remark 2.5. • $\forall v \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}, \langle v, v \rangle \in 2\mathbb{Z}$

- $E, E' \in \text{Coh}(X), v(E) = v(E') \Rightarrow (\text{rank}(E), c_1(E), c_2(E)) = (\text{rank}(E'), c_1(E'), c_2(E'))$
- $\forall v \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}, \exists E \in \text{Coh}(X) \text{ s.t. } v(E) = v$

Definition 2.6 (Moduli stacks of torsion-free sheaves). X : K3 surface, $v \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$

Then, we define the moduli stack of torsion-free sheaves $\mathcal{M}^{\text{tf}}(v)$ as the following category.

1. Objects : (U, E) , where

- $U : \text{Sch}/\mathbb{C}$,
- E : quasi-coherent sheaf of finite presentation on $X \times_{\mathbb{C}} U (=:\mathcal{X})$, flat/ U
s.t. E_t : torsion-free sheaves on $\mathcal{X}_t = X_{k(t)}$ with $v(E_t) = v$ ($\forall t \in U$)

2. Morphisms : from (U, E) to $(U', E') \rightsquigarrow (\varphi : U \rightarrow U', \alpha : \varphi^* E \rightarrow E' : \text{isomorphism})$

Definition 2.7 (Stacks of Harder-Narasimhan filtration). $v, v_1, v_2 \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$

$$\mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v) := \left\{ E \in \mathcal{M}^{\text{tf}}(v) \left| \begin{array}{l} \exists (0 \subset E_1 \subset E) : \text{Harder-Narasimhan filtration} \\ \text{with } v(E_1) = v_1, v(E/E_1) = v_2 \end{array} \right. \right\}$$

$$\mathcal{M}^{\text{ss}}(v) := \{ E \in \mathcal{M}^{\text{tf}}(v) \mid E : \text{semistable} \}$$

3 Main Theorem

Theorem 3.1. Let X be a K3 surface of $\rho(X) = 1$, $v_0 \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$: primitive, $m \in \mathbb{Z}$.
 $v := mv_0$. We assume $[v]_0 = 2$ and v satisfies one of the following disjoint conditions.

- (a) : $\langle v, v \rangle > 0$
- (b) : $\langle v, v \rangle < -2$, $\langle v_0, v_0 \rangle \neq -2$
- (c) : $\langle v, v \rangle = 0, -2$, v : primitive

then, we have the irreducible decomposition of $\mathcal{M}^{\text{tf}}(v)$ as follows.

$$\mathcal{M}^{\text{tf}}(v) = \overline{\mathcal{M}^{\text{ss}}(v)} \cup \bigcup_{(v_1, v_2) \in S \cup S_{\text{even}}} \overline{\mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)}$$

, where (we always assume $v_1, v_2 \in \mathbb{Z} \oplus \text{Pic}(X) \oplus \mathbb{Z}$)

$$I := \{(v_1, v_2) \mid v_1 + v_2 = v, \text{rank}(v_1) = \text{rank}(v_2) = 1\}$$

$$J := \{(v_1, v_2) \mid \langle v_1, v_2 \rangle < 1\} \quad K := \{(v_1, v_2) \mid 2[v_1]_1 = 2[v_2]_1 = [v]_1\}$$

$$S := \begin{cases} (I \cap J) \setminus K & \text{if (a) or (c)} \\ I \setminus K & \text{if (b)} \end{cases} \quad S_{\text{even}} := \begin{cases} I \cap J \cap K & \text{if (a) or (c), and } 2 \mid [v]_1 \\ I \cap K & \text{if (b), and } 2 \mid [v]_1 \\ \emptyset & \text{otherwise} \end{cases}$$

Moreover, we can classify the irreducible components into 3 types according to the general members of them.

$$\begin{aligned} \forall E \in \mathcal{M}^{\text{ss}}(v) & \text{ is semistable} \\ (v_1, v_2) \in S & \Rightarrow \forall E \in \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v) \text{ is not } \mu\text{-semistable} \\ (v_1, v_2) \in S_{\text{even}} & \Rightarrow \forall E \in \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v) \text{ is not semistable but } \mu\text{-semistable} \end{aligned}$$

Remark 3.2. v satisfies (b) $\Rightarrow \mathcal{M}^{\text{ss}}(v)$: empty category

Corollary 3.3. The dimension of $\mathcal{M}^{\text{tf}}(v)$ at $\forall E \in \mathcal{M}^{\text{tf}}(v)$ is the following.

$$\begin{aligned} v \text{ satisfies (a) or (c)} & \Rightarrow \dim_E \mathcal{M}^{\text{tf}}(v) = \begin{cases} \langle v, v \rangle + 1 & (E \in \mathcal{M}^{\text{ss}}(v) \cup \bigcup_{\langle v_1, v_2 \rangle \geq 1} \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)) \\ \langle v_1, v_1 \rangle + \langle v_2, v_2 \rangle + \langle v_1, v_2 \rangle + 2 & (E \in \bigcup_{\langle v_1, v_2 \rangle < 1} \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)) \end{cases} \\ v \text{ satisfies (b)} & \Rightarrow \dim_E \mathcal{M}^{\text{tf}}(v) = \langle v_1, v_1 \rangle + \langle v_2, v_2 \rangle + \langle v_1, v_2 \rangle + 2 \end{aligned}$$

Remark 3.4. By Yoshioka([Kimura-Yoshioka11], [Kurihara-Yoshioka08]), it is known that

$$\begin{aligned} \dim \mathcal{M}^{\text{ss}}(v) & := \sup_{E \in \mathcal{M}^{\text{ss}}(v)} (\dim_E \mathcal{M}^{\text{ss}}(v)) = \langle v, v \rangle + 1 \\ \dim \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v) & := \sup_{E \in \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)} (\dim_E \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)) = \langle v_1, v_1 \rangle + \langle v_2, v_2 \rangle + \langle v_1 + v_2 \rangle + 2 \end{aligned}$$

But $\dim_E \mathcal{M}^{\text{tf}}(v)$ is NOT necessarily equal to $\dim \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)$ for $E \in \mathcal{M}_{(v_1, v_2)}^{\text{HN}}(v)$.

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